

## Specifications

Input	<input type="checkbox"/> RTD, <input type="checkbox"/> thermocouple, <input type="checkbox"/> current, <input type="checkbox"/> voltage
Output	<input type="checkbox"/> power supply voltage, 5 A
Power Supply	<input type="checkbox"/> 230 VAC, <input type="checkbox"/> 115 VAC, <input type="checkbox"/> 12...24 VAC/DC
Consumption	less than 1.5 VA
Measurement Error	$\leq \pm 0.3\%$ from span
Temperature Drift	$\leq 0.02\%$ from span for 1 °C
Operating Temperature / Humidity	-10...65 °C / 0...85% RH
Protection Class	IP66

v7-04.10



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## PROGRAMMABLE CONTROLLER

# RT38-Y

## OPERATION MANUAL



Please read this Operation Manual before mounting and operating!  
Save the Manual for future references!

Table 1

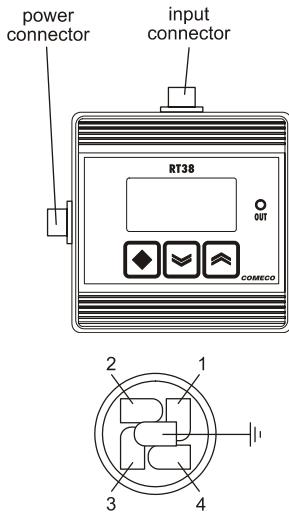
Parameter	Symbol	Description
<b>Configuration Parameters</b> (These parameters are part of Configuration level)		
Input Type	$i_{nP}$	The type of the signal that can be connected to the device input
Display Offset	$dF5$	Specifies a constant to be added to the measured input value
Point Position	$P_{nL}$	The display decimal point position
Filter Time	$F_t$	Specifies the relative time constant of the input filter
Filter Band	$F_b$	Specifies a zone around the measured value, within which the filter is active
Unit	$U_{nL}$	Temperature measurement unit
Input Low	$i_{Lo}$	Display low range, corresponding to the low signal range of a linear input
Input High	$i_{hi}$	Display high range, corresponding to the high signal range of a linear input
<b>Parameters of the control algorithm</b> (These parameters are part of Parametric level)		
Hysteresis	$HYS$	Relay switching differential
Direction	$d_{ir}$	Relay action direction
Hold	$HLd$	Holds the output reaction
<b>Parameter of Basic (operating) level</b>		
Set Point	$S.P$	Control set-point value
<b>Keyboard locking Parameter</b> (This parameter is part of Hidden level)		
Lock Keyboard	$L_{oc}$	Keyboard locking mode

Value	Unit	Notes
RTD	-	$P_{t1}$ ( $Pt50$ ), $P_{t2}$ ( $Pt100$ ), $P_{t3}$ ( $Pt500$ ), $P_{t4}$ ( $Pt1000$ ), $P_{t5}$ ( $Pt46-GOST$ ), $P_{t6}$ ( $Pt50-GOST$ ), $P_{t7}$ ( $Pt100-GOST$ ), $C_{u1}$ ( $Cu50, 1.426$ ), $C_{u2}$ ( $Cu100, 1.426$ ), $C_{u3}$ ( $Cu50, 1.428$ ), $C_{u4}$ ( $Cu100, 1.428$ )
T/C	-	$E_{cJ}$ ( $T/C "J"$ ), $E_{cK}$ ( $T/C "K"$ ), $E_{cT}$ ( $T/C "T"$ )
current	-	$4.20$ (4...20 mA), $0.20$ (0...20 mA)
voltage	-	$0.10$ (0...10 V)
-199 ... 999	ISU	OFFSET
x1, x0.1	-	when indicating values with the input-signal measurement unit (ISU); $_{.1}$ (tens not shown), $_{.1}$ (tens shown within the -19.9...99.9 range)
0 ... 100	-	
0 ... 100	-	
$\square_{nL} P_F$	-	This parameter makes sense ONLY in case of a temperature sensor!
-199 ... 999	ISU	This parameter makes sense ONLY in case of a linear input signal!
-199 ... 999	ISU	This parameter makes sense ONLY in case of a linear input signal!
0 ... 100	ISU	
$_{-7}_{-1} F_{-1}$	-	$_{-7}_{-1}$ (relay ON under set point), $F_{-1}$ (relay ON over set point)
0 ... 999	sec.	
-199 ... 999	ISU	For temperature input, the set point is limited for different sensor types!
$\square_{FF}, \square_{on}, S.P.E.RLL$	-	$\square_{FF}$ (totally unlocked), $\square_{on}$ (Configuration level locked), $S.P.E$ (only set-point adjustment enabled), $RLL$ (totally locked)

## Overview

RT38-Y is a cheap programmable ON/OFF controller, designed for direct control over temperature or other processes when coupled with a temperature or other sensor. The device is equipped with a 3-digit LED display and a control relay transferring the power supply voltage to an external actuator. RT38-Y is available in 2 universal-input versions – RTD (for 7 selectable Pt<sub>x</sub> and 4 Cux sensor types) and T/C (for 3 selectable thermocouples) – as well as in versions for linear current and voltage signals.

## Wiring



### Power wiring

- ◆ Connect the right power supply voltage for your device (see '**Specifications**') via pins #3 (line) and #4 (neutral) of the power connector.
- ◆ Use pins #2 (line) and #1 (neutral) of the power connector to wire the output.

### Input wiring

- ◆ In case of an RT38-Y with linear input, connect the input signal through the device input connector as follows:  
pin #1 - common;  
pin #2 - input;  
pin #3 - Vaux (+).
- ◆ To connect sensor to a RT38-Y with RTD or T/C input, use the pins of the input connector in the following way:  
pin #1 - common;  
pin #2 - RTD or T/C (-);  
pin #3 - RTD or T/C (+).
- ◆ In either case, leave pin #4 unconnected.



### Important note:

*Power supply must be turned off during the wiring!*

## Input Filtration

### Low-pass filter

This first-order filter acts ONLY within a certain band around filter output value. This has been designed to cut periodic noises outside the communication signal spectrum.

- ◆ Filter operation is defined by two parameters:  
**Filter Time** (defines filter time constant) and  
**Filter Band** (defines filter active band around filter output value).
- ◆ If the newly measured value differs from the filter output by more than **Filter Band**, the filter resets with a new initial output value (newly measured value).

## Electro-Magnetic Interference (EMI) Issues

- ◆ All signal wires must be shielded. They must not be packaged together with power cables!
- ◆ Never lay the signal wires close to inductive or capacitive noise sources, such as relays, contactors, motors, etc.!
- ◆ All shields have to be grounded ONLY at one end, as closer as possible to the controller terminals!
- ◆ Avoid sharing supply lines with powerful consumers, especially with inductive loads, switched on and off.
- ◆ To stop unwelcome interference signals entering through the power supply lines, use shielded 1:1 isolation transformer!
- ◆ Shunt all switched (not only those switched by the controller) inductive consumers with special suppression networks: RC group and varistor - for AC loads, or diode - for DC loads.
- ◆ If the controller operates in a very powerful EMI area, it has to be mounted inside a grounded metal shielding box!

## Parameter Programming

### Controller parameters

RT38-Y is a programmable device whose service behavior is determined by a set of parameters. All the parameters, along with their names, symbols, and value ranges, are given in Table 1.

### Setting numerical parameter value

- ◆ Enter parameter value adjustment mode (see '**Program Levels**').
- ◆ The whole part of the value together with the left zeroes appears on the display, and the rightmost digit blinks.
- ◆ To increase or decrease the blinking digit value, use respectively or .
- ◆ The 2 rightmost digits can accept values from **0** to **9**, and the leftmost digit can also accept the values **-** and **1**.
- ◆ To select another digit, press .
- ◆ Confirm the adjusted value by pressing simultaneously + .
- ◆ If the new value has not been confirmed and no key has been pressed for a certain period of time, value adjustment automatically ceases, and the parameter retains its initial value.

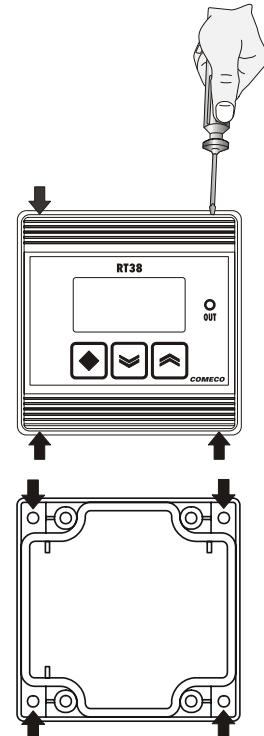
### Setting symbolic parameter value

- ◆ Enter parameter value adjustment mode (see '**Program Levels**').
- ◆ Read the blinking parameter value.
- ◆ To change the value, use and , and to confirm, press + .
- ◆ If the new value has not been confirmed and no key has been pressed for a certain period of time, value adjustment automatically ceases, and the parameter retains its initial value.

## Error Messaging

- ◆ **R - 7** (over range) - display value over 999 or sensor damaged (broken).
- ◆ **L - J** (under range) - display value under -199 or sensor damaged (shorted out).
- ◆ **F RL** (fail) - device memory error; if error still exists after restart, the unit must be returned for repair.
- ◆ **E.n.C** (not calibrated) - all factory calibrations are set to default and the accuracy can not be guaranteed!
- ◆ **E.S.P** (error in Set Point) - incorrect Set Point value; check and readjust.
- ◆ **E.H S** (error in Hysteresis) - incorrect Hysteresis value; check and readjust.
- ◆ **- - -** (noise / initial check) - too noisy input signal; also shows the initial device check at power-on.

## Mounting



### Direct in-process mounting

Fit RT38-Y to the object of control through the mounting accessory of the built-in sensor.

### Wall mounting

- ◆ Insert the tip of a suitable screwdriver into one of the openings between the lower and the upper cap on the front panel. Use the screwdriver as a lever to open the caps.
- ◆ Unscrew the four screws and remove the part of the box containing the electronic module and the front panel.



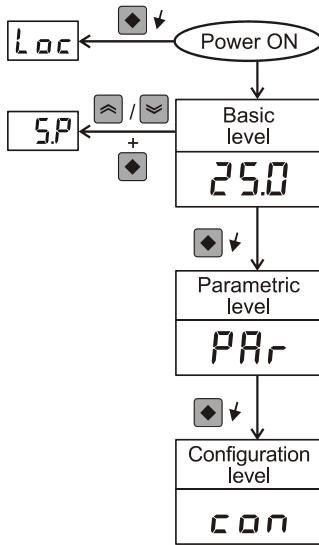
*For subsequent installations, skip this step because the mounting screws are already accessible through the four corner holes under the front panel caps.*

- ◆ Fix the box to the wall with proper mounting screws through the four back holes on the terminal box.
- ◆ Put the electronic module and the front panel caps back.

### DIN-rail mounting

Your RT38-Y can also be easily mounted on every 35 mm rail conforming to EN50022 by the means of a special DIN-rail clamp, which has to be ordered separately.

## Program Levels



### Basic level

- ◆ At power-on, RT38-Y enters Basic level. At this level, the device indicates the measured input value (PV) with a resolution, according to the Point Position parameter.
- ◆ To enter Set Point value adjustment mode, press  $\triangleleft + \blacklozenge$  or  $\triangleright + \blacklozenge$ .

### Parametric level

This level contains the control algorithm parameters.

- ◆ Enter from Basic level by pressing and holding  $\blacklozenge$  until  $PAr$  appears on the display. Release the key.
- ◆ Choose a parameter with  $\triangleleft$  and  $\triangleright$ .
- ◆ To enter parameter value adjustment mode, press  $\blacklozenge + \triangleleft$ .
- ◆ If no key has been pressed for a while, the device automatically returns to Basic level, storing all confirmed changes.
- ◆ For quick exiting and saving, use key combination  $\triangleleft + \triangleright$ . Message  $S\ddot{e}o$  confirms the adjustments.

### Configuration level

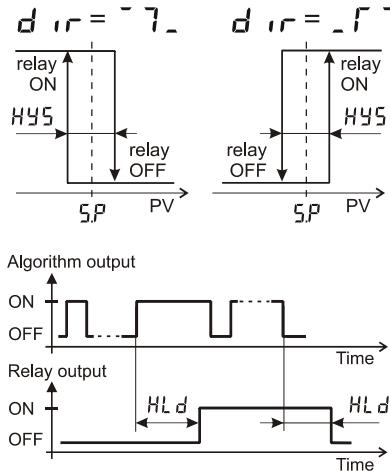
This level contains the configuration parameters of the device.

- ◆ Enter from Basic level by pressing and holding  $\blacklozenge$  until  $con$  appears.
- ◆ To access and adjust the configuration parameters, follow the algorithm described in 'Parametric level'.

### Hidden level

- ◆ Hold  $\blacklozenge$  depressed while turning the power on and until  $Loc$  appears.
- ◆ Set keyboard locking mode.

## Output Control



### Output control operation

- ◆ The control output operates according to the control algorithm parameters.
- ◆ The output deactivates when an error has been detected (see 'Error messaging').

### ON/OFF control algorithm

The static characteristic of a relay controlled by an ON/OFF algorithm is shown on the left drawing.

### Output hold

For eliminating undesirable switches of the alarm output, additional parameter (Hold) is assigned to hold the output reaction for certain period of time.